

Cross Products

$$\bar{A} \times \bar{B} = |\bar{A}| |\bar{B}| \sin \theta$$

$$|\bar{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$\bar{A} \times \bar{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$\bar{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$
 $\bar{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$

$$= \hat{i} (A_y B_z - A_z B_y) - \hat{j} (A_x B_z - A_z B_x) + \hat{k} (A_x B_y - A_y B_x)$$

$$\vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$\vec{A} \times (\vec{B} + \vec{C}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C}$$

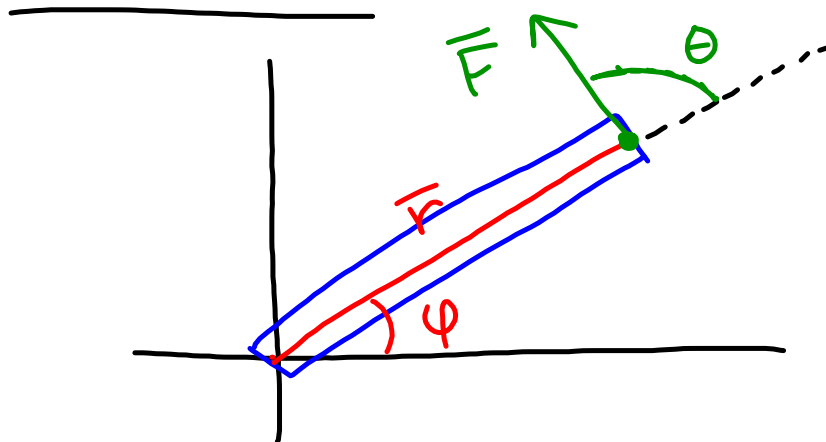
- Solution to a cross product is a vector perpendicular to the other two vectors.

PRACTICE - CROSS PRODUCTS AND ROTATIONAL STATICS

$$1) \quad \hat{i} - 3\hat{j} + 2\hat{k} \quad \text{and} \quad 5\hat{i} - \hat{j} - 4\hat{k}$$

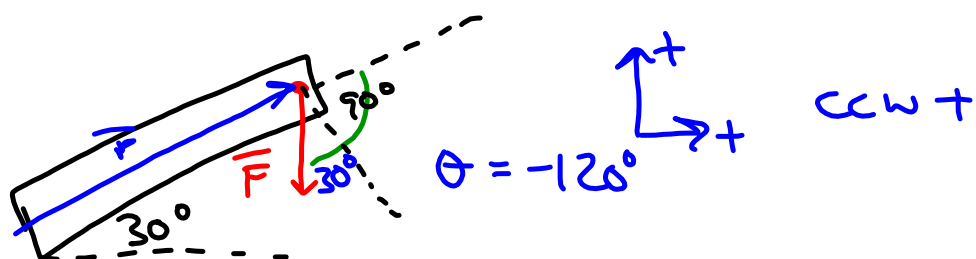
$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -3 & 2 \\ 5 & -1 & -4 \end{vmatrix} = \hat{i} [(-3)(-4) - (2)(-1)] \\ - \hat{j} [(1)(-4) - (2)(5)] \\ + \hat{k} [(1)(-1) - (-3)(5)] \\ = 14\hat{i} + 14\hat{j} + 14\hat{k}$$

TORQUE



θ is measured
ccw from dashed
line that extends
radially from r

4)



$$\tau = |\vec{r}| |\vec{F}| \sin \theta$$

$$= (0.2 \text{ m})(100 \text{ N}) \sin(-120^\circ)$$

$$= -17 \text{ N}\cdot\text{m}$$

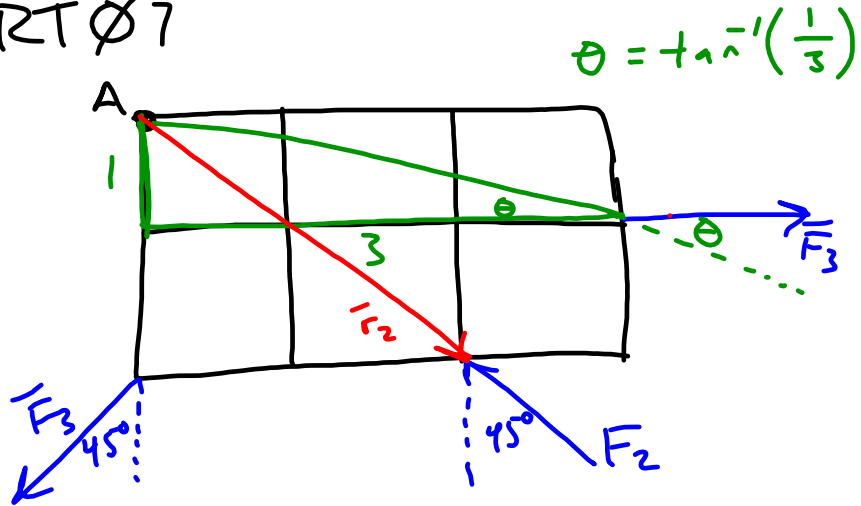
- Net Torque:

$$\sum \vec{\tau} = \vec{\tau}_1 + \vec{\tau}_2 + \vec{\tau}_3 + \dots$$

TIPERS

- BG - QRTØ7

A)



$$\sum \vec{\tau} = \vec{\tau}_1 + \vec{\tau}_2 + \vec{\tau}_3$$

$$= |\vec{r}_1| |\vec{F}_1| \sin \theta_1 + |\vec{r}_2| |\vec{F}_2| \sin \theta_2 + |\vec{r}_3| |\vec{F}_3| \sin \theta_3$$

$$= (2)(F) \sin(45^\circ) + (2\sqrt{2})(F) \sin(180^\circ) + (\sqrt{10})(F) \sin(18.44^\circ)$$

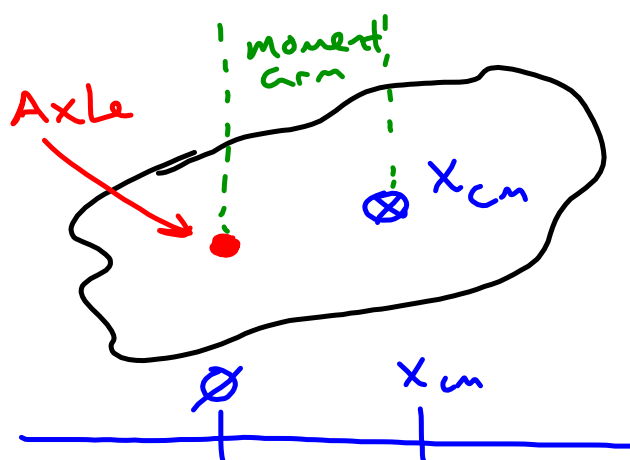
$$= (-0.414)F$$

↑ negative means clockwise!

B. zero

C. zero

GRAVITATIONAL TORQUE



$$\tau = -M g x_{cm}$$