

$$\frac{d^2 \theta}{dt^2} = -a_g \theta$$

$$\theta(t) = \theta_{\max} \cos(\omega t + \varphi)$$

$$\dot{\theta}(t) = -\theta_{\max} \omega \sin(\omega t + \varphi)$$

derivative
with
respect
to time

$$\ddot{\theta}(t) = -\theta_{\max} \omega^2 \cos(\omega t + \varphi)$$

$$\omega = 2\pi f$$

$$\omega = \sqrt{\frac{a_g}{L}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{a_g}{L}}$$

$$T = 2\pi \sqrt{\frac{L}{a_g}}$$

angular
frequency

$$1) \quad v(t) = - \cancel{\theta}_{\max} \omega \sin(\omega t + \varphi) \quad 1$$

$$v = - \cancel{\theta}_{\max}^A \sqrt{\frac{g}{L}}$$

$$\omega = \sqrt{\frac{g}{L}}$$

$$A \quad \cancel{\theta}_{\max} = v \sqrt{\frac{L}{g}}$$

$$v = 0.25 \text{ m/s}$$

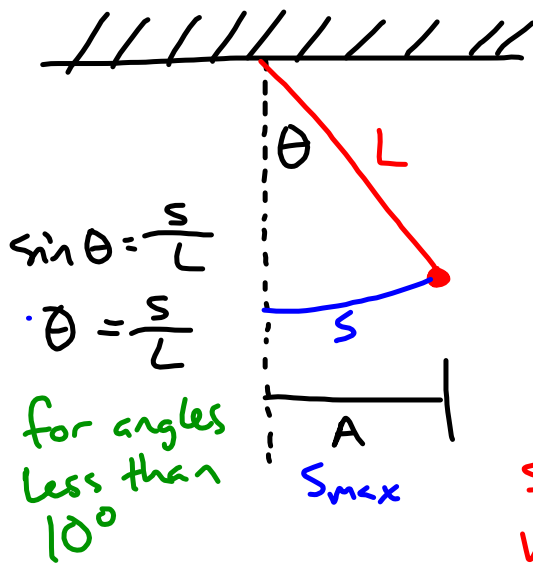
$$L = 0.3 \text{ m}$$

$$A = (0.25 \text{ m/s}) \sqrt{\frac{0.3 \text{ m}}{9.8 \text{ m/s}^2}}$$

$$= 0.0437 \text{ m}$$

$$A = s_{\max} = \theta_{\max} L$$

$$\theta_{\max} = \frac{s_{\max}}{L} = \frac{0.0437 \text{ m}}{0.3 \text{ m}} = 0.146 \text{ rad}$$



$$s(t) = A \cos(\omega t + \varphi)$$

$$v(t) = -A\omega \sin(\omega t + \varphi)$$

$$a(t) = -A\omega^2 \cos(\omega t + \varphi)$$

$$s = A = \theta L$$

$$s_{\max} = A = \theta_{\max} L$$

$$v_{\max} = A\omega = A \sqrt{\frac{a_g}{L}} = \theta_{\max} L \sqrt{\frac{a_g}{L}}$$

$$a_{\max} = A\omega^2 = \frac{A a_g}{L} = \theta_{\max} a_g$$